

## LAMPIRAN

### KODE PROGRAM

```
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 16, 2);

float arus0, arus2, arus3, arustotal, vout0, vout2, vout3, K0, K2, K3;
int adc0, adc2, adc3;
int dataMax0, dataMax2, dataMax3;

void setup()
{
    lcd.begin();
    pinMode(A0, INPUT_PULLUP);
    pinMode(A2, INPUT_PULLUP);
    pinMode(A3, INPUT_PULLUP);
    dataMax0 = adc0;
    dataMax2 = adc2;
    dataMax3 = adc3;
    pinMode(9, OUTPUT);
    pinMode(12, OUTPUT);
}

void loop()
{
    for ( int i = 0; i < 1000; i++) {
        adc0 = analogRead(A0);
        adc2 = analogRead(A2);
        adc3 = analogRead(A3);
        if ( adc0 > dataMax0) dataMax0 = adc0;
        if ( adc2 > dataMax2) dataMax2 = adc2;
        if ( adc3 > dataMax3) dataMax3 = adc3;
        delay(1);
    }
    vout0 = dataMax0 * (5.0 / 1023);
    vout2 = dataMax2 * (5.0 / 1023);
    vout3 = dataMax3 * (5.0 / 1023);

    if (dataMax0 < 527) K0 = 0.36;
    else if (dataMax0 < 532) K0 = 0.4;
    else if (dataMax0 < 543) K0 = 0.47;
    else if (dataMax0 < 546) K0 = 0.47;
    else if (dataMax0 < 597) K0 = 0.82;
    else if (dataMax0 < 602) K0 = 0.85;
    else if (dataMax0 < 604) K0 = 1.20;
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else if (dataMax0 < 613) K0 = 0.93;  
  
if (dataMax2 < 528) K2 = 0.38;  
else if (dataMax2 < 534) K2 = 0.45;  
else if (dataMax2 < 544) K2 = 0.50;  
else if (dataMax2 < 549) K2 = 0.55;  
else if (dataMax2 < 600) K2 = 0.87;  
else if (dataMax2 < 604) K2 = 0.93;  
else if (dataMax2 < 607) K2 = 1.28;  
else if (dataMax2 < 615) K2 = 0.98;  
  
if (dataMax3 < 524) K3 = 0.51;  
else if (dataMax3 < 527) K3 = 0.57;  
else if (dataMax3 < 533) K3 = 0.64;  
else if (dataMax3 < 535) K3 = 0.66;  
else if (dataMax3 < 564) K3 = 1.08;  
else if (dataMax3 < 566) K3 = 1.06;  
else if (dataMax3 < 568) K3 = 1.47;  
else if (dataMax3 < 575) K3 = 1.19;  
  
arus0 = (abs(vout0 - 2.50) / 0.185) - K0;  
arus2 = (abs(vout2 - 2.50) / 0.185) - K2;  
arus3 = (abs(vout3 - 2.50) / 0.100) - K3;  
arustotal = arus0 + arus2 + arus3;  
if (arus0 < 0.03)arus0 = 0;  
if (arus2 < 0.03)arus2 = 0;  
if (arus3 < 0.03)arus3 = 0;  
  
lcd.clear();  
lcd.setCursor(0, 0);  
lcd.print(dataMax0);  
lcd.setCursor(0, 1);  
lcd.print(arus0);  
  
lcd.setCursor(5, 0);  
lcd.print(dataMax2);  
lcd.setCursor(5, 1);  
lcd.print(arus2);  
  
lcd.setCursor(10, 0);  
lcd.print(dataMax3);  
lcd.setCursor(10, 1);  
lcd.print(arus3);  
  
digitalWrite(9, LOW);  
digitalWrite(12, LOW);
```

```
if (arustotal>2.00) digitalWrite(9, HIGH);
if ((arus0>1.65) && (arustotal>2.00)) digitalWrite(12, HIGH);

dataMax0 = 0;
dataMax2 = 0;
dataMax3 = 0;

arus0 = 0;
arus2 = 0;
arus3 = 0;

vout0 = 0;
vout2 = 0;
vout3 = 0;
delay(1000);

}
```