

LAMPIRAN

Listing Program

```
#include <LiquidCrystal.h>

LiquidCrystal lcd(5, 6, 7, 8, 9, 10);

//RS,E,D4,D5,D6,D7

// TCS230 or TCS3200 pins wiring to Arduino

#define S0 A0

#define S1 A1

#define S2 A2

#define S3 A3

#define sensorOut 2

//tombol START

#define tombol 4

//sensor jarak

#define triger 1

#define echo 0

#define BAT A4

int blueFrequency=0;

int uw;

//jarak

int mydistance;
```

```
float rawV;  
  
float batC;  
  
//int batC//  
  
//int graph;;  
  
void setup()  
{  
  // Setting the outputs  
  pinMode(S0, OUTPUT);  
  pinMode(S1, OUTPUT);  
  pinMode(S2, OUTPUT);  
  pinMode(S3, OUTPUT);  
  
  // Setting the sensorOut as an input  
  pinMode(sensorOut, INPUT);  
  pinMode(tombol, INPUT_PULLUP);  
  
  pinMode(echo, INPUT_PULLUP);  
  pinMode(triger, OUTPUT);  
  
  // Setting frequency scaling to 20%  
  digitalWrite(S0,HIGH);  
  digitalWrite(S1,LOW);  
  
  lcd.begin(16, 2);
```

```

lcd.clear();

lcd.setCursor(0,0);

lcd.print("RADIOMETER");

lcd.setCursor(0,1);

lcd.print("UKUR BLUE LIGHT");

delay(1000);

lcd.clear();

lcd.setCursor(0,0);

lcd.print("TIYAS SULISTIYA");

lcd.setCursor(0,1);

lcd.print("20153010096");

delay(800);

}

void loop()
{
  while(1)
  {
    lcd.clear();

    lcd.setCursor(0,0);

    lcd.print("MULAI PENGUKURAN");

    lcd.setCursor(0,1);

    lcd.print("TEKAN START ");

    if(digitalRead(tombol)==LOW)break;
  }
}

```

```
delay (100);  
}  
lcd.clear();  
delay(200);  
  
while(1)  
{  
int jarak=read_ultra();  
  
rawV=analogRead(4);  
batC=(rawV*5)/1024;  
  
if(blueFrequency <= 3)  
{  
uw=1;  
}  
else if(blueFrequency ==3)  
{  
uw=1998*(blueFrequency)-3995;  
}  
else if(blueFrequency >= 3 && blueFrequency <= 4)  
{  
uw=-149*(blueFrequency)+2446;  
}  
else if(blueFrequency >= 4 && blueFrequency <= 5)
```

```
{
uw=-531*(blueFrequency)+3974;
}
else if(blueFrequency >= 5 && blueFrequency <= 6)
{
uw=-19*(blueFrequency)+1414;
}
else if(blueFrequency >= 6 && blueFrequency <= 7)
{
uw=-110*(blueFrequency)+1960;
}
else if(blueFrequency >=7 && blueFrequency<=10)
{
uw=-146*(blueFrequency)+2310;
}
else if (blueFrequency>=10&&blueFrequency<=13)
{
uw=-56.667*(blueFrequency)+1416.7;
}
else if (blueFrequency>=13&&blueFrequency<=15)
{
uw=-50*(blueFrequency)+1320;
}
else if (blueFrequency>=15&&blueFrequency<=17)
{
```

```
uw=-25*(blueFrequency)+945;
}
else if (blueFrequency>=17&&blueFrequency<=20)
{
uw=-15.667*(blueFrequency)+786.33;
}
else if (blueFrequency>=20&&blueFrequency<=23)
{
uw=-19.333*(blueFrequency)+859.67;
}
else if (blueFrequency>=23&&blueFrequency<=26)
{
uw=-21*(blueFrequency)+898;
}
else if (blueFrequency>=26&&blueFrequency<=30)
{
uw=-12.75*(blueFrequency)+683.5;
}
else if (blueFrequency>=30&&blueFrequency<35)
{
uw=-5.2*(blueFrequency)+457;
}
else if (blueFrequency>=35&&blueFrequency<=40)
{
uw=-7.6*(blueFrequency)+541;
```

```
}  
  else if (blueFrequency>=45&&blueFrequency<=50)  
  {  
    uw=-4.4*(blueFrequency)+410;  
  }  
  else if (blueFrequency>=50&&blueFrequency<=55)  
  {  
    uw=-3.8*(blueFrequency)+380;  
  }  
  else if (blueFrequency>=55&&blueFrequency<=60)  
  {  
    uw=-3.2*(blueFrequency)+347;  
  }  
  else if (blueFrequency>=65&&blueFrequency<=75)  
  {  
    uw=-1.7*(blueFrequency)+252.5;  
  }  
  
  else // (>=75)  
  {  
    uw=0;  
  }
```

```
lcd.clear();
```

```
lcd.setCursor(0,0);
```



```
lcd.print("Jarak :");  
lcd.print(jarak);  
lcd.print("CM");  
lcd.setCursor(0,1);  
lcd.print("uW/cm2:");  
lcd.print(uw);  
//lcd.setCursor(10,1);  
//lcd.print("B:");  
//lcd.print(blueFrequency);  
lcd.setCursor(12,1);  
lcd.print(batC);  
lcd.setCursor(15,1);  
lcd.print("V");
```

```
bacabiru_TCS3200();  
}}
```

```
float read_ultra()  
{  
    float mydistance;  
    // suara ultrasonik on  
    digitalWrite(triger, HIGH);  
    delayMicroseconds(10);  
    // suara ultrasonik off
```

```

digitalWrite(triger, LOW);

// baca pulsa dan konvert ke cm

mydistance=(float)pulseIn(echo,HIGH)/58;

return mydistance;
}

void bacabiru_TCS3200()
{
unsigned long buf=0;

for(int i=0;i<800;i++)
{
digitalWrite(S2,LOW);

digitalWrite(S3,HIGH);

//delay(10);

// Reading the output frequency

blueFrequency= pulseIn(sensorOut, LOW);

buf+=blueFrequency;

//delay(100);

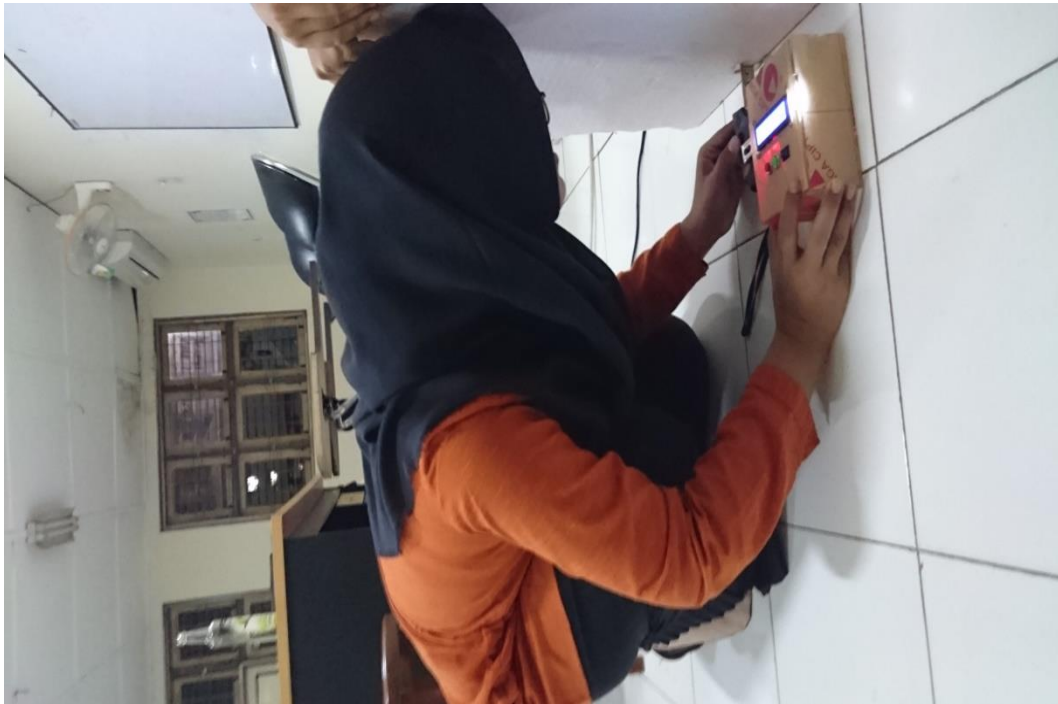
}

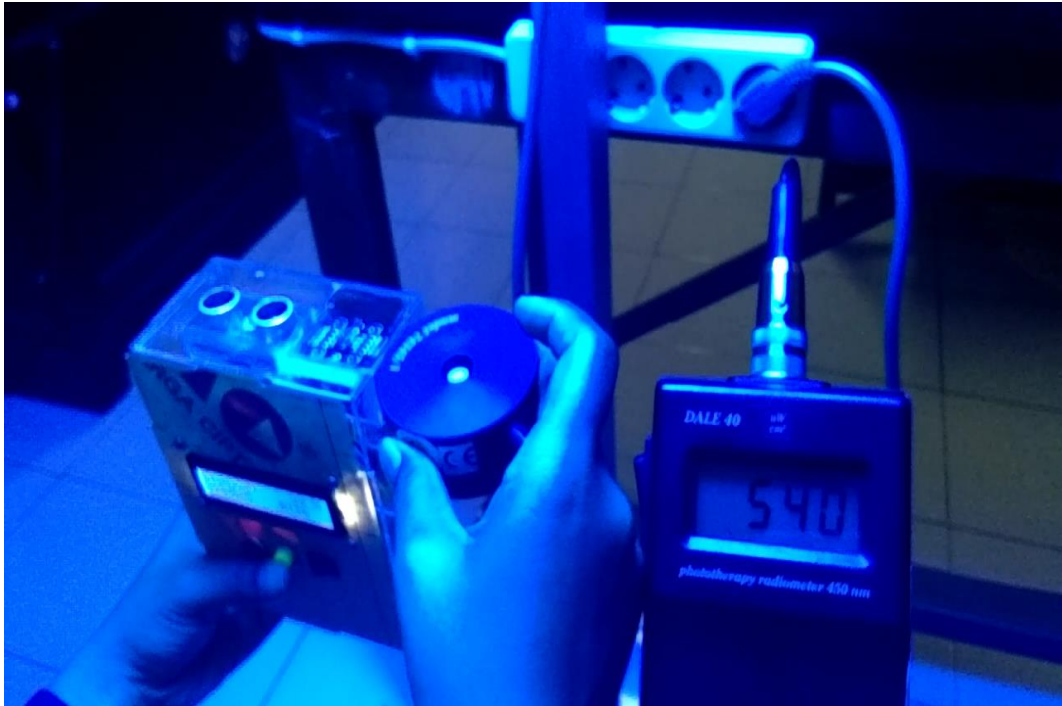
blueFrequency = buf/800;

}

```

Foto Pengambilan Data





Penghitungan

1. Analisis Hasil Perhitungan Pengukuran Jarak Terhadap Meteran

a. Jarak 5 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{5 + 5 + 6 + 5 + 5 + 5}{6}$$

$$\bar{X} = \frac{31}{6}$$

$$\bar{X} = 5,16 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{5 - 5,16}{5} \times 100\%$$

$$\% \text{ Error} = 3,3 \%$$

b. Jarak 10 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{10 + 10 + 10 + 10 + 10 + 10}{6}$$

$$\bar{X} = \frac{60}{6}$$

$$\bar{X} = 10 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{10 - 10}{10} \times 100\%$$

$$\% \text{ Error} = 0 \%$$

c. Jarak 15 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{15 + 15 + 15 + 15 + 15 + 15}{6}$$

$$\bar{X} = \frac{90}{6}$$

$$\bar{X} = 15 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{15 - 15}{15} \times 100\%$$

$$\% \text{ Error} = 0 \%$$

d. Jarak 20 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{20 + 20 + 20 + 20 + 21 + 20}{6}$$

$$\bar{X} = \frac{121}{6}$$

$$\bar{X} = 20,17 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{20 - 20,17}{20} \times 100\%$$

$$\% \text{ Error} = 0,8 \%$$

e. Jarak 25 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{25 + 25 + 26 + 25 + 25 + 24}{6}$$

$$\bar{X} = \frac{149}{6}$$

$$\bar{X} = 24,83 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{25 - 24,83}{25} \times 100\%$$

$$\% \text{ Error} = -0,6 \%$$

f. Jarak 30 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{30 + 29 + 30 + 30 + 30 + 30}{6}$$

$$\bar{X} = \frac{179}{6}$$

$$\bar{X} = 29,83 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{30 - 29,83}{30} \times 100\%$$

$$\% \text{ Error} = -0,5 \%$$

g. Jarak 35 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{35 + 35 + 35 + 36 + 35 + 35}{6}$$

$$\bar{X} = \frac{211}{6}$$

$$\bar{X} = 35,17 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{35 - 35,17}{35} \times 100\%$$

$$\% \text{ Error} = 0 \%$$

h. Jarak 30 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{40 + 40 + 40 + 40 + 40 + 40}{6}$$

$$\bar{X} = \frac{240}{6}$$

$$\bar{X} = 40 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{40 - 40}{40} \times 100\%$$

$$\% \text{ Error} = 0 \%$$

i. Jarak 45 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{45 + 45 + 45 + 45 + 45 + 45}{6}$$

$$\bar{X} = \frac{270}{6}$$

$$\bar{X} = 45 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{45 - 45}{45} \times 100\%$$

$$\% \text{ Error} = 0 \%$$

j. Jarak 50 cm

1). Rata-Rata Data Pengukuran Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{50 + 50 + 50 + 50 + 49 + 50}{6}$$

$$\bar{X} = \frac{299}{6}$$

$$\bar{X} = 49,83 \text{ cm}$$

2). Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{50 - 49,83}{50} \times 100\%$$

$$\% \text{ Error} = -0,3 \%$$

2. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 30 cm

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum X_i}{n}$$

$$\bar{X} = \frac{1145 + 1176 + 1286 + 1296 + 1304 + 1312}{6}$$

$$\bar{X} = \frac{7519}{6}$$

$$\bar{X} = 1253,16 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum X_i}{n}$$

$$\bar{X} = \frac{1190 + 1190 + 1300 + 1300 + 1300 + 1319}{6}$$

$$\bar{X} = \frac{7599}{6}$$

$$\bar{X} = 1266,5 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{1253,16 - 1266,5}{1253,16} \times 100\%$$

$$\% \text{ Error} = -1,06 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum(X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(1190 - 1266,5)^2 + (1190 - 1266,5)^2 + (1300 - 1266,5)^2 + (1300 - 1266,5)^2 + (1300 - 1266,5)^2 + (1319 - 1266,5)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{17827,5}{5}}$$

$$SD = 59,71$$

e. Ketidakpastian (U_a)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{59,71}{\sqrt{6}}$$

$$U_a = \frac{59,71}{2,4}$$

$$U_a = 24,87$$

3. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 40 cm

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum X_i}{n}$$

$$\bar{X} = \frac{902 + 884 + 833 + 821 + 806 + 820}{6}$$

$$\bar{X} = \frac{5066}{6}$$

$$\bar{X} = 844,33 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{920 + 912 + 890 + 840 + 780 + 840}{6}$$

$$\bar{X} = \frac{5182}{6}$$

$$\bar{X} = 863,67 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{844,3 - 863,6}{844,3} \times 100\%$$

$$\% \text{ Error} = -2,29 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum (X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(920 - 863,67)^2 + (912 - 863,67)^2 + (890 - 863,67)^2 + (840 - 863,67)^2 + (780 - 863,67)^2 + (840 - 863,67)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{2857,44}{5}}$$

$$SD = 53,4$$

e. Ketidakpastian (Ua)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{53,4}{\sqrt{6}}$$

$$U_a = \frac{53,4}{2,4}$$

$$U_a = 53,4$$

4. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 50 cm

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{624 + 654 + 656 + 676 + 671 + 664}{6}$$

$$\bar{X} = \frac{3945}{6}$$

$$\bar{X} = 657,5 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{680 + 680 + 640 + 680 + 680 + 680}{6}$$

$$\bar{X} = \frac{4040}{6}$$

$$\bar{X} = 673,3 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{657,5 - 673,3}{657,5} \times 100\%$$

$$\% \text{ Error} = -2,4 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum (X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(680 - 673,3)^2 + (680 - 673,3)^2 + (640 - 673,3)^2 + (680 - 673,3)^2 + (680 - 673,3)^2 + (680 - 673,3)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{291,05}{5}}$$

$$SD = 7,62$$

e. Ketidakpastian (U_a)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{7,62}{\sqrt{6}}$$

$$U_a = \frac{7,62}{2.4}$$

$$U_a = 3,17$$

5. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 46 cm dititik Kanan

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{528 + 526 + 521 + 528 + 528 + 526}{6}$$

$$\bar{X} = \frac{3157}{6}$$

$$\bar{X} = 526,16 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{570 + 545 + 545 + 545 + 545 + 545}{6}$$

$$\bar{X} = \frac{3295}{6}$$

$$\bar{X} = 549,16 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{X_n - \bar{X}}{X_n} \times 100\%$$

$$\% \text{ Error} = \frac{526,16 - 549,16}{526,16} \times 100\%$$

$$\% \text{ Error} = -4,37 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum(X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(570 - 549,16)^2 + (545 - 549,16)^2 + (545 - 549,16)^2 + (545 - 549,16)^2 + (545 - 549,16)^2 + (545 - 549,16)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{608,17}{5}}$$

$$SD = 11,02$$

e. Ketidakpastian (Ua)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{11,02}{\sqrt{6}}$$

$$U_a = \frac{11,02}{2,4}$$

$$U_a = 4,59$$

6. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 46 cm dititik Tengah

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{773 + 759 + 770 + 769 + 759 + 729}{6}$$

$$\bar{X} = \frac{4559}{6}$$

$$\bar{X} = 759,83 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{735 + 795 + 793 + 793 + 793 + 736 + 735}{6}$$

$$\bar{X} = \frac{4585}{6}$$

$$\bar{X} = 764,16 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{759,83 - 764,16}{759,83} \times 100\%$$

$$\% \text{ Error} = -0,57 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum (X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(735 - 764,16)^2 + (793 - 764,16)^2 + (793 - 764,16)^2 + (793 - 764,16)^2 + (736 - 764,16)^2 + (735 - 764,16)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{4988,8}{5}}$$

$$SD = 31,58$$

e. Ketidakpastian (U_a)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{31,58}{\sqrt{6}}$$

$$U_a = \frac{31,58}{2,4}$$

$$U_a = 13,15$$

7. Analisis Hasil Perhitungan Pengukuran Iradiasi *Blue Light* Pada Jarak 46 cm dititik Kiri

a. Rata-Rata Data Kalibrator

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{533 + 507 + 519 + 547 + 551 + 542}{6}$$

$$\bar{X} = \frac{3199}{6}$$

$$\bar{X} = 533,16 \mu W/cm^2$$

b. Rata-Rata Data Modul

$$\bar{X} = \frac{\sum Xi}{n}$$

$$\bar{X} = \frac{488 + 504 + 520 + 520 + 545 + 545}{6}$$

$$\bar{X} = \frac{3122}{6}$$

$$\bar{X} = 520,33 \mu W/cm^2$$

c. Error

$$\% \text{ Error} = \frac{Xn - \bar{X}}{Xn} \times 100\%$$

$$\% \text{ Error} = \frac{533,16 - 520,33}{533,16} \times 100\%$$

$$\% \text{ Error} = -2,4 \%$$

d. Standar Deviasi

$$SD = \sqrt{\frac{\sum(X_i - \bar{X})^2}{n - 1}}$$

$$SD = \sqrt{\frac{(488 - 520,33)^2 + (504 - 520,33)^2 + (520 - 520,33)^2 + (520 - 520,33)^2 + (545 - 520,33)^2 + (545 - 520,33)^2}{6 - 1}}$$

$$SD = \sqrt{\frac{1949,13}{5}}$$

$$SD = 19,74$$

e. Ketidakpastian (U_a)

$$U_a = \frac{SD}{\sqrt{n}}$$

$$U_a = \frac{19,74}{\sqrt{6}}$$

$$U_a = \frac{19,74}{2,4}$$

$$U_a = 8,225$$